

# Idoc

## Modules

Modules
<a href="#">IO.Sockets</a>
<a href="#">debugConfig</a>
<a href="#">rinApp</a>
<a href="#">rinLibrary.K400</a>
<a href="#">rinLibrary.K412</a>
<a href="#">rinLibrary.L401</a>
<a href="#">rinLibrary.IdocUsage</a>
<a href="#">rinLibrary.rinCSV</a>
<a href="#">rinLibrary.rinDebug</a>
<a href="#">rinLibrary.rinINI</a>
<a href="#">rinLibrary.rinRIS</a>
<a href="#">rinLibrary.rinVT100</a>
<a href="#">rinLibrary.rincon</a>
<a href="#">rinSystem</a>
<a href="#">rinSystem.rinSockets</a>
<a href="#">rinSystem.rinTimers</a>

<a href="#">IO.Sockets</a>	Module that manages IO functions
<a href="#">debugConfig</a>	Default configuration for the debugger.
<a href="#">rinApp</a>	Module manager for L401
<a href="#">rinLibrary.K400</a>	Library for K400 application support.
<a href="#">rinLibrary.K412</a>	Libary for the K412, providing easy functionality for interfacing with all aspects of the device
<a href="#">rinLibrary.L401</a>	Libary for the L401, providing easy functionality for interfacing with all aspects of the device
<a href="#">rinLibrary.IdocUsage</a>	Documentation of the Idoc features
<a href="#">rinLibrary.rinCSV</a>	Functions for working with .CSV files and creating multi-table databases
<a href="#">rinLibrary.rinDebug</a>	Offer functions for converting variables into strings for debugging
<a href="#">rinLibrary.rinINI</a>	Services for saving and restoring settings in a table to .INI config file
<a href="#">rinLibrary.rinRIS</a>	Creates a connection to the M4223
<a href="#">rinLibrary.rinVT100</a>	Functions for working with VT100 terminal interface
<a href="#">rinLibrary.rincon</a>	Creates a connection to the M4223
<a href="#">rinSystem</a>	Framework for interfacing with the L401 for advanced applications
<a href="#">rinSystem.rinSockets</a>	Offer functions for sockets that are compatible with the app framework
<a href="#">rinSystem.rinTimers</a>	Offer functions for timers that are compatible with the app framework

generated by [LDoc 1.2](#)

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## Module IO.Sockets

Module that manages IO functions

### Functions

<a href="#">makeSocket (fdin, fdout)</a>	Makes an imitation socket from a LUA file descriptor that can be used with select.
<a href="#">connectDevice ()</a>	Connects to the user IO
<a href="#">getMsg ()</a>	Get a message from the connection

### Functions

#### [makeSocket \(fdin, fdout\)](#)

Makes an imitation socket from a LUA file descriptor that can be used with select.

**Parameters:**

- *fdin*: File descriptor to take input from
- *fdout*: File descriptor to send output to

**Returns:**

An imitation socket with the methods getfd, dirty, receive, send, close

#### [connectDevice \(\)](#)

Connects to the user IO

**Returns:**

the connection (not necessary for use)

#### [getMsg \(\)](#)

Get a message from the connection

**Returns:**

message

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Default configuration for the debugger.

This can be overridden if the user calls a script with rinapp with arguments

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Module manager for L401

**Functions**

<a href="#">addK400 (model, ip, portA, portB)</a>	Called to connect to the K400 instrument, and establish the timers, streams and other services
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<a href="#">cleanup ()</a>	Called to restore the system to initial state by shutting down services enabled by configure()
----------------------------	--

**Functions****addK400 (model, ip, portA, portB)**

Called to connect to the K400 instrument, and establish the timers, streams and other services

**Parameters:**

- *model*: Software model expected for the instrument (eg "K401")
- *ip*: IP address for the socket, "127.1.1.1" used as a default
- *portA*: port address for the SERA socket (2222 used as default)
- *portB*: port address for the SERB socket (2223 used as default)

**Returns:**

device object for this instrument

**cleanup ()**

Called to restore the system to initial state by shutting down services enabled by configure()

generated by [LDoc 1.2](#)

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**Module rinLibrary.K400**

Library for K400 application support.

Provides wrappers for all device services

**Register Functions**

<a href="#">sysRegisters</a>	System Registers.
<a href="#">rdgRegisters</a>	Instrument Reading Registers.
<a href="#">usrRegisters</a>	Instrument User Variables.
<a href="#">productRegisters</a>	K412 Product Registers.
<a href="#">rinCMD</a>	Main Instrument Commands.
<a href="#">sendReg (cmd, reg, data)</a>	Called to send command to a register but not wait for the response
<a href="#">sendRegWait (cmd, reg, data, t)</a>	Called to send command and wait for response
<a href="#">readReg (reg)</a>	Called to read register contents
<a href="#">writeReg (reg, data)</a>	Called to write data to an instrument register
<a href="#">exReg (reg, data)</a>	Called to run a register execute command with data as the execute parameter

**General Utilities**

<a href="#">lcdControl (mode)</a>	Called to setup LCD control
<a href="#">model</a>	Called to connect the K400 library to a socket and a system
<a href="#">getRegDP (reg)</a>	Called to read a register value and return value and dp position Used to work out the dp position of a register value so subsequent reads can use the hexadecimal format and convert locally using toFloat
<a href="#">saveSettings ()</a>	Called to save any changed settings and re-initialise instrument
<a href="#">configure ()</a>	Called to configure the instrument library
<a href="#">toPrimary (v)</a>	Called to convert a floating point value to a decimal integer based on then primary instrument weighing settings
<a href="#">toFloat (data, dp)</a>	called to convert hexadecimal return string to a floating point number

**Streaming**

<a href="#">streamCallback (data, err)</a>	Divide the data stream up and run the relevant callbacks
<a href="#">addStream (streamReg, callback, onChange)</a>	Add a stream to the device (must be connected) Takes parameter 'change' (default) to run callback only if data received changed, 'always' otherwise
<a href="#">removeStream (streamReg)</a>	Remove a stream from the device
<a href="#">streamCleanup ()</a>	Called to cleanup any unused streaming
<a href="#">setStreamFreq (freq)</a>	Set the frequency used for streaming

**Status Monitoring**

<a href="#">sysstatus</a>	Status Bits for REG_SYSSTATUS.
<a href="#">statusCallback (data, err)</a>	Called when status changes are streamed
<a href="#">setStatusCallback (stat, callback)</a>	Set the callback function for a status bit
<a href="#">setupStatus ()</a>	Setup status monitoring via a stream
<a href="#">setRTCStatus (s)</a>	Control the use of RTC status bit
<a href="#">setRDGStatus (num)</a>	Control the use of reading count status bit.
<a href="#">setIOSTatus ()</a>	private function
<a href="#">enableIOStatus (IO)</a>	sets IO status IO bit to recognise this IO
<a href="#">releaseIOStatus (IO)</a>	sets IO status IO bit to ignore this IO
<a href="#">endStatus ()</a>	Cancel status handling

**Key Handling**

<a href="#">keys</a>	Keys.
<a href="#">setupKeys ()</a>	Setup key handling stream
<a href="#">endKeys (flush)</a>	Cancel keypress handling
<a href="#">setKeyCallback (key, callback)</a>	Set the callback function for an existing key
<a href="#">keygroups</a>	Key Groups.
<a href="#">sendKey (key, status)</a>	Send an artificial key press to the instrument

**LCD Services**

<a href="#">writeTopLeft (s)</a>	Write string to Top Left of LCD, curTopLeft is set to s
<a href="#">writeTopRight (s)</a>	Write string to Top Right of LCD, curTopRight is set to s
<a href="#">writeBotLeft (s)</a>	Write string to Bottom Left of LCD, curBotLeft is set to s
<a href="#">writeBotRight (s)</a>	Write string to Bottom Right of LCD, curBotRight is set to s
<a href="#">setAutoTopAnnun (reg)</a>	link register address with Top annunciators to update automatically
<a href="#">setAutoTopLeft (reg)</a>	link register address with Top Left display to update automatically.
<a href="#">setAutoBotLeft (reg)</a>	link register address with Bottom Left display to update automatically
<a href="#">BotAnnuns</a>	Bottom LCD Annunciators
<a href="#">setBitsBotAnnuns (d)</a>	Sets the annunciator bits for Bottom Annunciators
<a href="#">clrBitsBotAnnuns (d)</a>	Clears the annunciator bits for Bottom Annunciators

<b>rotWAIT (dir)</b>	Rotate the WAIT annunciator
<b>TopAnnuns</b>	Top LCD Annunciators
<b>setBitsTopAnnuns (d)</b>	Sets the annunciator bits for Top Annunciators
<b>clrBitsTopAnnuns (d)</b>	Clears the annunciator bits for Top Annunciators
<b>Units</b>	Main Units
<b>Other</b>	Additional modifiers on bottom display
<b>writeTopUnits (units)</b>	Set top units
<b>writeBotUnits (units, other)</b>	Set bottom units
<b>restoreLcd ()</b>	Called to restore the LCD to its default state

### Buzzer Control

<b>setBuzzLen (len)</b>	Called to set the length of the buzzer sound
<b>buzz (times)</b>	Called to trigger instrument buzzer

### Analogue Output Control

<b>setAnalogSource (src)</b>	Set the analog output type
<b>setAnalogType (typ)</b>	Set the analog output type
<b>setAnalogClip (c)</b>	Control behaviour of analog output outside of normal range.
<b>setAnalogRaw (v)</b>	Sets the analog output to minimum 0 through to maximum 50,000
<b>setAnalogVal (val)</b>	Sets the analogue output to minimum 0.0 through to maximum 1.0
<b>setAnalogPC (val)</b>	Sets the analogue output to minimum 0% through to maximum 100%
<b>setAnalogVolt (val)</b>	Sets the analogue output to minimum 0.0V through to maximum 10.0V
<b>setAnalogCur (val)</b>	Sets the analogue output to minimum 4.0 through to maximum 20.0 mA

### Setpoint Control

<b>turnOn (IO)</b>	Turns IO Output on
<b>turnOff (IO)</b>	Turns IO Output off
<b>turnOnTimed (IO, t)</b>	Turns IO Output on
<b>enableOutput (IO)</b>	Sets IO Output under LUA control
<b>releaseOutput (IO)</b>	Sets IO Output under instrument control
<b>setpParam (setp, reg, v)</b>	Private function
<b>setpRegAddress (setp, reg)</b>	returns actual register address for a particular setpoint parameter
<b>setNumSetp (n)</b>	Set the number of Setpoints
<b>setpTarget (setp, target)</b>	Set Target for setpoint
<b>setpIO (setp, IO)</b>	Set which Output the setpoint controls
<b>Types</b>	Setpoint Types.
<b>setpLogic (setp, v)</b>	Set the Logic for the setpoint controls
<b>Alarms</b>	Setpoint Alarms Types.
<b>setpAlarm (setp, v)</b>	Set the Alarm for the setpoint
<b>setpName (setp, v)</b>	Set the Name of the setpoint
<b>Source</b>	Setpoint Source Types.
<b>setpHys (setp, v)</b>	Set the Hysteresis for of the setpoint controls

### Dialog Control

<b>getKey (keyGroup)</b>	Called to get a key from specified key group
<b>isEditing ()</b>	Check to see if editing routines active
<b>edit (prompt, def, typ)</b>	Called to prompt operator to enter a value
<b>editReg (reg)</b>	Called to edit value of specified register
<b>delayCallback ()</b>	Private function
<b>delay (t)</b>	Called to delay for t msec while keeping event handlers running
<b>askOKCallback (key, state)</b>	Private function
<b>askOK (prompt, q)</b>	Prompts operator and waits for OK or CANCEL key press
<b>selectOption (prompt, options, def, loop)</b>	Prompts operator to select from a list of options using arrow keys and KEY_OK

### Printing Utilities

<b>printCustomTransmit (tokenStr, comPort)</b>	Send custom print token string to instrument comms port
<b>reqCustomTransmit (tokenStr)</b>	Called to request response based on custom transmit token string

### Real Time Clock

<b>sendDateFormat (fmt)</b>	sets the instrument date format
<b>RTCread (d)</b>	Read Real Time Clock data from instrument into local RTC table
<b>RTCTick ()</b>	Called every second to update local RTC
<b>RTCtoString ()</b>	Returns formated date/time string Private function
<b>RTCdateFormat (first, second, third)</b>	Sets the order of the date string.byte
<b>REG_ADC_ZERO</b>	Commands TODO: Finalise these commands to return proper error messages etc
<b>zero ()</b>	<>
<b>tare ()</b>	<>

<a href="#">presetTare ()</a>	<>
<a href="#">gross ()</a>	<>
<a href="#">net ()</a>	<>
<a href="#">grossNetToggle ()</a>	<>

## Register Functions

Functions to read, write and execute commands on instrument registers directly

### sysRegisters

System Registers.

#### Fields:

- [REG\\_SOFTMODEL](#): Software model eg. "K401"
- [REG\\_SOFTVER](#): Software Version eg "V1.00"
- [REG\\_SERIALNO](#): Serial Number

### rdgRegisters

Instrument Reading Registers.

#### Fields:

- [REG\\_ADCSAMPLE](#): Sample number of current reading
- [REG\\_SYSSTATUS](#): System Status Bits
- [REG\\_SYSERR](#): System Error Bits
- [REG\\_ABSMV](#): Absolute mV/V reading (10,000 = 1mV/V)
- [REG\\_GROSSNET](#): Gross or Net reading depending on operating mode
- [REG\\_GROSS](#): Gross weight
- [REG\\_NET](#): Net Weight
- [REG\\_TARE](#): Tare Weight
- [REG\\_PEAKHOLD](#): Peak Hold Weight
- [REG\\_MANHOLD](#): Manually Held weight
- [REG\\_GRANDTOTAL](#): Accumulated total
- [REG\\_ALTGROSS](#): Gross weight in secondary units
- [REG\\_RAWADC](#): Raw ADC reading (2,560,000 = 1.0 mV/V)
- [REG\\_ALTNET](#): Net weight in secondary units
- [REG\\_FULLSCALE](#): Fullscale weight

### usrRegisters

Instrument User Variables.

#### Fields:

- [REG\\_USERID\\_NAME1](#): Names of 5 User ID strings
- [REG\\_USERID\\_NAME2](#):
- [REG\\_USERID\\_NAME3](#):
- [REG\\_USERID\\_NAME4](#):
- [REG\\_USERID\\_NAME5](#):
- [REG\\_USERNUM\\_NAME1](#): Names of 5 User ID numbers
- [REG\\_USERNUM\\_NAME2](#):
- [REG\\_USERNUM\\_NAME3](#):
- [REG\\_USERNUM\\_NAME4](#):
- [REG\\_USERNUM\\_NAME5](#):
- [REG\\_USERID1](#): Data for 5 User ID strings
- [REG\\_USERID2](#): the first 2 are integers
- [REG\\_USERID3](#): the last 3 are weight values
- [REG\\_USERID4](#):
- [REG\\_USERIDS](#):
- [REG\\_USERNUM1](#): Data for 5 User ID numbers
- [REG\\_USERNUM2](#):
- [REG\\_USERNUM3](#):
- [REG\\_USERNUM4](#):
- [REG\\_USERNUM5](#):

### productRegisters

K412 Product Registers.

#### Fields:

- [REG\\_ACTIVE\\_PRODUCT\\_NO](#): Read the Active Product Number, Write to set the active product by number
- [REG\\_ACTIVE\\_PRODUCT\\_NAME](#): Read the Active Product Name, Write to set Active Product by name
- [REG\\_CLR\\_ALL\\_TOTALS](#): Clears all product totals (EXECUTE)
- [REG\\_CLR\\_DOCKET\\_TOTALS](#): Clears all docket sub-totals (EXECUTE)
- [REG\\_SELECT\\_PRODUCT\\_NO](#): Read the Selected Product Number, Write to set the Selected product by number
- [REG\\_SELECT\\_PRODUCT\\_NAME](#): Read the Selected Product Name, Write to set the Selected product by Name
- [REG\\_SELECT\\_PRODUCT\\_DELETE](#): Delete Selected Product (EXECUTE)
- [REG\\_SELECT\\_PRODUCT\\_RENAME](#): Write to change name of selected product

**rinCMD**

Main Instrument Commands.

**Fields:**

- *CMD\_RDLIT*: Read literal data
- *CMD\_RDFINALHEX*: Read data in hexadecimal format
- *CMD\_RDFINALDEC*: Read data in decimal format
- *CMD\_WRFINALHEX*: Write data in hexadecimal format
- *CMD\_WRFINALDEC*: Write data in decimal format
- *CMD\_EX*: Execute with data as execute parameter

**sendReg (cmd, reg, data)**

Called to send command to a register but not wait for the response

**Parameters:**

- *cmd*: CMD\_ command
- *reg*: REG\_ register
- *data*: to send

**sendRegWait (cmd, reg, data, t)**

Called to send command and wait for response

**Parameters:**

- *cmd*: CMD\_ command
- *reg*: REG\_ register
- *data*: to send
- *t*: timeout in msec

**Returns:**

1. reply received from instrument, nil if error
2. err error string if error received, nil otherwise

**readReg (reg)**

Called to read register contents

**Parameters:**

- *reg*: REG\_ register

**Returns:**

1. data received from instrument, nil if error
2. err error string if error received, nil otherwise

**writeReg (reg, data)**

Called to write data to an instrument register

**Parameters:**

- *reg*: REG\_ register
- *data*: to send

**exReg (reg, data)**

Called to run a register execute command with data as the execute parameter

**Parameters:**

- *reg*: REG\_ register
- *data*: to send

**General Utilities**

General Functions for configuring the instrument

**lcdControl (mode)**

Called to setup LCD control

**Parameters:**

- *mode*: is 'lua' to control display from script or 'default' to return control to the default instrument application

**model**

Called to connect the K400 library to a socket and a system

**getRegDP (reg)**

Called to read a register value and return value and dp position. Used to work out the dp position of a register value so subsequent reads can use the hexadecimal format and convert locally using toFloat

**Parameters:**

- *reg*: register to read

**Returns:**

register value number and dp position

**saveSettings ()**

Called to save any changed settings and re-initialise instrument

**configure ()**

Called to configure the instrument library

**Returns:**

nil if ok or error string if model doesn't match

**toPrimary(v)**

Called to convert a floating point value to a decimal integer based on then primary instrument weighing settings

**Parameters:**

- *v*: is value to convert

**Returns:**

floating point value suitable for a WRFINALDEC

**toFloat (data, dp)**

called to convert hexadecimal return string to a floating point number

**Parameters:**

- *data*: returned from \_CMD\_RDFINALHEX or from stream
- *dp*: decimal position

**Returns:**

floating point number

## Streaming

This section is for functions associated with streaming registers

**streamCallback (data, err)**

Divide the data stream up and run the relevant callbacks

**Parameters:**

- *data*: Data received from register
- *err*: Potential error message

**addStream (streamReg, callback, onChange)**

Add a stream to the device (must be connected) Takes parameter 'change' (default) to run callback only if data received changed, 'always' otherwise

**Parameters:**

- *streamReg*: Register to stream from (\_M.REG\_\*)
- *callback*: Function to bind to streaming register
- *onChange*: Change parameter return streamReg indentity

**removeStream (streamReg)**

Remove a stream from the device

**Parameters:**

- *streamReg*: Register to be removed(\_M.REG\_\*)

**streamCleanup ()**

Called to cleanup any unused streaming

**setStreamFreq (freq)**

Set the frequency used for streaming

**Parameters:**

- *freq*: Frequency of streaming (\_M.STM\_FREQ\_\*)

## Status Monitoring

Functions are associated with the status monitoring

**sysstatus**

Status Bits for REG\_SYSSTATUS.

**Fields:**

- *SYS\_OVERLOAD*: Scale overloaded
- *SYS\_UNDERLOAD*: Scale underload
- *SYS\_ERR*: Error active
- *SYS\_SETUP*: Instrument in setup mode
- *SYS\_CALINPROG*: Instrument calibration in progress
- *SYS\_MOTION*: Weight unstable
- *SYS\_CENTREOFZERO*: Centre of Zero (within 0.25 divisions of zero)
- *SYS\_ZERO*: Weight within zero band setting
- *SYS\_NET*: Instrument in Net mode

**statusCallback (data, err)**

Called when status changes are streamed

**Parameters:**

- *data*: Data on status streamed
- *err*: Potential error message

**setStatusCallback (stat, callback)**

Set the callback function for a status bit

**Parameters:**

- *stat*: STAT\_ status bit
- *callback*: Function to run when there is an event on change in status

**setupStatus ()**

Setup status monitoring via a stream

**setRTCStatus (s)**

Control the use of RTC status bit

**Parameters:**

- *s*: true to enable RTC change monitoring, false to disable

**setRDGStatus (num)**

Control the use of reading count status bit. This is useful if weight readings are not collected via an on change stream register directly

**Parameters:**

- *num*: Sets amount of readings to trigger a reading count status change

**setIOSTatus ()**

private function

**enableIOStatus (IO)**

sets IO status IO bit to recognise this IO

**Parameters:**

- *IO* is output 1..32

**releaseIOStatus (IO)**

sets IO status IO bit to ignore this IO

**Parameters:**

- *IO* is output 1..32

**endStatus ()**

Cancel status handling

**Key Handling**

Functions associated with the handing key presses

**keys**

Keys.

**Fields:**

- *KEY\_O*:
- *KEY\_I*:

- KEY\_Z;
- KEY\_3;
- KEY\_4;
- KEY\_5;
- KEY\_6;
- KEY\_7;
- KEY\_8;
- KEY\_9;
- KEY\_POWER;
- KEY\_TARE;
- KEY\_SEL;
- KEY\_F1;
- KEY\_F2;
- KEY\_F3;
- KEY\_PLUSMINUS;
- KEY\_DP;
- KEY\_CANCEL;
- KEY\_UP;
- KEY\_DOWN;
- KEY\_OK;
- KEY\_SETUP;
- KEY\_PWR\_ZERO;
- KEY\_PWR\_TARE;
- KEY\_PWR\_SEL;
- KEY\_PWR\_F1;
- KEY\_PWR\_F2;
- KEY\_PWR\_F3;
- KEY\_PWR\_CANCEL;

---

**setupKeys ()**

Setup key handling stream

---

**endKeys (flush)**

Cancel keypress handling

**Parameters:**

- *flush*: Flush the current keypresses that have not yet been handled

---

**setKeyCallback (key, callback)**

Set the callback function for an existing key

**Parameters:**

- *key*: to monitor (KEY\_\*)
- *callback*: Function to run when there is an event for that key. Callback function parameters are key (.KEY\_OK etc) and state ('short' or 'long')

**Usage:**

```
local function F1Pressed(key, state)
    if state == 'short' then
        dbg.info('F1 pressed')
    end
    return true -- F1 handled here so don't send back to instrument for handling
end
dwi.setKeyCallback(dwi.KEY_F1, F1Pressed)
```

---

**keygroups**

Key Groups.

**Fields:**

- *keyGroup.all*:
- *keyGroup.primary*:
- *keyGroup.functions*:
- *keyGroup.keypad*:
- *keyGroup.numpad*:
- *keyGroup.cursor*:
- *keyGroup.extended*: Set the callback function for an existing key group

---

**sendKey (key, status)**

Send an artificial key press to the instrument

**Parameters:**

- *key*: (KEY\_\*)
- *status*: 'long' or 'short'

## LCD Services

Functions to configure the LCD

### writeTopLeft (s)

Write string to Top Left of LCD, curTopLeft is set to s

**Parameters:**

- *s*: string to display

### writeTopRight (s)

Write string to Top Right of LCD, curTopRight is set to s

**Parameters:**

- *s*: string to display

### writeBotLeft (s)

Write string to Bottom Left of LCD, curBotLeft is set to s

**Parameters:**

- *s*: string to display

### writeBotRight (s)

Write string to Bottom Right of LCD, curBotRight is set to s

**Parameters:**

- *s*: string to display

### setAutoTopAnnun (reg)

link register address with Top annunciators to update automatically

**Parameters:**

- *reg*: address of register to link Top Announcer state to. Set to 0 to enable direct control of the area

### setAutoTopLeft (reg)

link register address with Top Left display to update automatically.

**Parameters:**

- *reg*: address of register to link Top Left display to. Set to 0 to enable direct control of the area

### setAutoBotLeft (reg)

link register address with Bottom Left display to update automatically

**Parameters:**

- *reg*: address of register to link Top Left display to. Set to 0 to enable direct control of the area

## BotAnnuns

Bottom LCD Annunciators

**Fields:**

- *BATTERY*
- *CLOCK*
- *BAT\_LC*
- *BAT\_MIDL*
- *BAT\_MIDH*
- *BAT\_HI*
- *BAT\_FULL*
- *WAIT*
- *WAIT45*
- *WAIT90*
- *WAIT135*
- *WAITALL*

### setBitsBotAnnuns (d)

Sets the annunciator bits for Bottom Annunciators

**Parameters:**

- *d* holds bit locations

### clrBitsBotAnnuns (d)

Clears the annunciator bits for Bottom Annunciators

**Parameters:**

- *d* holds bit locations

#### **rotWAIT (dir)**

Rotate the WAIT annunciator

**Parameters:**

- *dir*: 1 clockwise, -1 anticlockwise 0 no change

#### **TopAnnuns**

Top LCD Annunciators

**Fields:**

- *SIGMA*
- *BALANCE*
- *COZ*
- *HOLD*
- *MOTION*
- *NET*
- *RANGE*
- *ZERO*
- *BAL\_SEGA*
- *BAL\_SEGB*
- *BAL\_SEGC*
- *BAL\_SEGD*
- *BAL\_SEGE*
- *BAL\_SEGF*
- *BAL\_SEGG*
- *RANGE\_SEGADG*
- *RANGE\_SEGC*
- *RANGE\_SEGE*

#### **setBitsTopAnnuns (d)**

Sets the annunciator bits for Top Annunciators

**Parameters:**

- *d* holds bit locations

#### **clrBitsTopAnnuns (d)**

Clears the annunciator bits for Top Annunciators

**Parameters:**

- *d* holds bit locations

#### **Units**

Main Units

**Fields:**

- *UNITS\_NONE*
- *UNITS\_KG*
- *UNITS\_LB*
- *UNITS\_T*
- *UNITS\_G*
- *UNITS\_OZ*
- *UNITS\_N*
- *UNITS\_ARROW\_L*
- *UNITS\_P*
- *UNITS\_I*
- *UNITS\_ARROW\_H* REG\_DISP UNITS BIT SETTINGS

#### **Other**

Additional modifiers on bottom display

**Fields:**

- *UNITS\_OTHER\_PER\_H*
- *UNITS\_OTHER\_PER\_M*
- *UNITS\_OTHER\_PER\_S*
- *UNITS\_OTHER\_PC*
- *UNITS\_OTHER\_TOT*

#### **writeTopUnits (units)**

Set top units

**Parameters:**

- *units*: (.UNITS\_NONE etc)

**writeBotUnits (units, other)**

Set bottom units

**Parameters:**

- *units*: (.UNITS\_NONE etc)
- *other*: (.UNITS\_OTHER\_PER\_H etc)

**restoreLcd ()**

Called to restore the LCD to its default state

## Buzzer Control

Functions to control instrument buzzer

**setBuzzLen (len)**

Called to set the length of the buzzer sound

**Parameters:**

- *len*: - length of buzzer sound (BUZZ\_SHORT, BUZZ\_MEDIUM, BUZZ\_LONG)

**buzz (times)**

Called to trigger instrument buzzer

**Parameters:**

- *times*: - number of times to buzz, 1..4

## Analogue Output Control

Functions to configure and control the analogue output module

**setAnalogSource (src)**

Set the analog output type

**Parameters:**

- *src*: Source for output. Must be set to ANALOG\_COMMs to control directly

**setAnalogType (typ)**

Set the analog output type

**Parameters:**

- *typ*: Type for output (.CUR or .VOLT)

**setAnalogClip (c)**

Control behaviour of analog output outside of normal range. If clip is active then output will be clipped to the nominal range otherwise the output will drive to the limit of the hardware

**Parameters:**

- *c*: 0 for clipping disabled, 1 for clipping enabled

**setAnalogRaw (v)**

Sets the analog output to minimum 0 through to maximum 50,000

**Parameters:**

- *v*: value in raw counts (0..50000)

**setAnalogVal (val)**

Sets the analogue output to minimum 0.0 through to maximum 1.0

**Parameters:**

- *val*: value 0.0 to 1.0

**setAnalogPC (val)**

Sets the analogue output to minimum 0% through to maximum 100%

**Parameters:**

- *val*: value 0 to 100 %

**setAnalogVolt (val)**

Sets the analogue output to minimum 0.0V through to maximum 10.0V

**Parameters:**

- *val*: value 0.0 to 10.0

---

**setAnalogCur (val)**

Sets the analogue output to minimum 4.0 through to maximum 20.0 mA

**Parameters:**

- *val*: value 4.0 to 20.0

**Setpoint Control**

Functions to setup adn control setpoint outputs

---

**turnOn (IO)**

Turns IO Output on

**Parameters:**

- *IO* is output 1..32

**turnOff (IO)**

Turns IO Output off

**Parameters:**

- *IO* is output 1..32

**turnOnTimed (IO, t)**

Turns IO Output on

**Parameters:**

- *IO* is output 1..32
- *t*: time in milliseconds

**enableOutput (IO)**

Sets IO Output under LUA control

**Parameters:**

- *IO* is input 1..32

**releaseOutput (IO)**

Sets IO Output under instrument control

**Parameters:**

- *IO* is output 1..32

**setUpParam (setp, reg, v)**

Private function

**Parameters:**

- *setp*
- *reg*
- *v*

**setUpRegAddress (setp, reg)**

returns actual register address for a particular setpoint parameter

**Parameters:**

- *setp* is setpoint 1..16
- *reg* is REG\_SETP\_\*

**Returns:**

address of this registet for setpoint setp

---

**setNumSetp (n)**

Set the number of Setpoints

**Parameters:**

- *n* is the number of setpoints 0..8

---

**setUpTarget (setp, target)**

Set Target for setpoint

**Parameters:**

- *setp*: Setpoint 1..16

- *target*: Target value

### setpIO (setup, IO)

Set which Output the setpoint controls

**Parameters:**

- *setup* is setpoint 1..16
- *IO* is output 1..32, 0 for none

### Types

Setpoint Types.

**Fields:**

- *TYPE\_OFF*.
- *TYPE\_ON*
- *TYPE\_OVER*
- *TYPE\_UNDER*
- *TYPE\_COZ*
- *TYPE\_ZERA*
- *TYPE\_NET*
- *TYPE\_MOTION*
- *TYPE\_ERROR*
- *TYPE\_LGC\_AND*
- *TYPE\_LGC\_OR*
- *TYPE\_LGC\_XOR*
- *TYPE\_BUZZER* Set the TYPE of the setpoint controls

### setpLogic (setup, v)

Set the Logic for the setpoint controls

**Parameters:**

- *setup* is setpoint 1..16
- *v* is setpoint logic type (.LOGIC\_HIGH, .LOGIC\_LOW)

### Alarms

Setpoint Alarms Types.

**Fields:**

- *ALARM\_NONE*
- *ALARM\_SINGLE*
- *ALARM\_DOUBLE*
- *ALARM\_FLASH*

### setpAlarm (setup, v)

Set the Alarm for the setpoint

**Parameters:**

- *setup* is setpoint 1..16
- *v* is alarm type

### setpName (setup, v)

Set the Name of the setpoint

**Parameters:**

- *setup* is setpoint 1..16
- *v* is setpoint name (8 character string)

### Source

Setpoint Source Types.

**Fields:**

- *SOURCE\_GROSS*
- *SOURCE\_NET*
- *SOURCE\_DISP*
- *SOURCE\_ALT\_GROSS*
- *SOURCE\_ALT\_NET*
- *SOURCE\_ALT\_DISP*
- *SOURCE\_PIECE*
- *SOURCE\_REG* Set the data source of the setpoint controls

### setpHys (setup, v)

Set the Hysteresis for of the setpoint controls

**Parameters:**

- *setpx* is setpoint 1..16
- *v*: is setpoint hysteresis

## Dialog Control

Functions for user interface dialogues

### getKey (keyGroup)

Called to get a key from specified key group

**Parameters:**

- *keyGroup*: keyGroup.all is default group

**Returns:**

key (KEY\_), state ('short','long','up')

### isEditing ()

Check to see if editing routines active

**Returns:**

true of editing false otherwise

### edit (prompt, def, typ)

Called to prompt operator to enter a value

**Parameters:**

- *prompt*: string displayed on bottom right LCD
- *def*: default value
- *typ*: type of value to enter ('integer','number','string')

**Returns:**

value and true if ok pressed at end

### editReg (reg)

Called to edit value of specified register

**Parameters:**

- *reg*: is the address of the register to edit

### delayCallback ()

Private function

### delay (t)

Called to delay for t msec while keeping event handlers running

**Parameters:**

- *t*: delay time in msec

### askOKCallback (key, state)

Private function

**Parameters:**

- *key*:
- *state*:

### askOK (prompt, q)

Prompts operator and waits for OK or CANCEL key press

**Parameters:**

- *prompt*: string to put on bottom right LCD
- *q*: string to put on bottom left LCD

**Returns:**

either KEY\_OK or KEY\_CANCEL

### selectOption (prompt, options, def, loop)

Prompts operator to select from a list of options using arrow keys and KEY\_OK

**Parameters:**

- *prompt*: string to put on bottom right LCD
- *options*: table of option strings
- *def*: default selection string,byte
- *loop*: If true, top option loops to the bottom option and vice versa

**Returns:**

selected string (default selection if KEY\_CANCEL pressed)

## Printing Utilities

Functions for printing

**printCustomTransmit (tokenStr, comPort)**

Send custom print token string to instrument comms port

**Parameters:**

- *tokenStr*: string containing custom print tokens
- *comPort*: - port to use PRINT\_SER1A (default) .. PRINT\_SER2B

**reqCustomTransmit (tokenStr)**

Called to request response based on custom transmit token string

**Parameters:**

- *tokenStr*: custom token string

## Real Time Clock

Functions to control Real Time Clock

**sendDateFormat (fmt)**

sets the instrument date format

**Parameters:**

- *fmt*: TM\_MMDDYYYY or TM\_DDMMYYYY

**RTCread (d)**

Read Real Time Clock data from instrument into local RTC table

**Parameters:**

- *d* 'date' or 'time' to read these fields only, or 'all' for both

**RTCTick ()**

Called every second to update local RTC

**RTCToString ()**

Returns formated date/time string Private function

**RTCDateFormat (first, second, third)**

Sets the order of the date string,byt

**Parameters:**

- *first* = 'day', 'month' or 'year'
- *second* = 'day', 'monht','year'
- *third* = 'day','month','year'

**REG\_ADC\_ZERO**

Commands TODO: Finalise these commands to return proper error messages etc

**zero ()**

<>

**tare ()**

<>

**presetTare ()**

<>

**gross ()**

<>

**net ()**

<>

**grossNetToggle ()**

&lt;&gt;

generated by [LDoc 1.2](#)

**Idoc****Index****Contents****Functions****Fields****Modules****IO.Sockets****debugConfig****rinApp****rinLibrary.K400****rinLibrary.K412****rinLibrary.L401****rinLibrary.IdocUsage****rinLibrary.rinCSV****rinLibrary.rinDebug****rinLibrary.rinINI****rinLibrary.rinRIS****rinLibrary.rinVT100****rinLibrary.rincon****rinSystem****rinSystem.rinSockets****rinSystem.rinTimers****Module rinLibrary.K412**

Library for the K412, providing easy functionality for interfacing with all aspects of the device

**Functions**

<b>connect (sock, system)</b>	Called to connect the L401 library to a socket and a system
<b>getRegDP (reg)</b>	Called to read a register value and return value and dp position Used to work out the dp position of a register value so subsequent reads can use the hexadecimal format and convert locally using toFloat
<b>saveSetting ()</b>	Called to save any changed settings and re-initialise instrument
<b>toPrimary (v)</b>	Called to convert a floating point value to a decimal integer based on then primary instrument weighing settings
<b>toFloat (data, dp)</b>	called to convert hexadecimal return string to a floating point number
<b>streamCallback (data, err)</b>	Divide the data stream up and run the relevant callbacks
<b>addStream (streamReg, callback, onChange)</b>	Add a stream to the device (must be connected) Takes parameter 'change' (default) to run callback only if data received changed, 'always' otherwise
<b>removeStream (streamReg)</b>	Remove a stream from the device
<b>streamCleanup ()</b>	Called to cleanup any unused streaming
<b>setStreamFreq (freq)</b>	Set the frequency used for streaming
<b>statusCallback (data, err)</b>	Called when status changes are streamed
<b>setStatusCallback (stat, callback)</b>	Set the callback function for a status bit
<b>setupStatus ()</b>	Setup status monitoring via a stream
<b>endStatus ()</b>	Cancel status handling
<b>keyCallback (data, err)</b>	Called when keys are streamed, send the keys to each group it is bound to in order of priority, until one of them returns true.
<b>setKeyCallback (key, callback)</b>	Set the callback function for an existing key
<b>setKeyGroupCallback (keyGroup, callback)</b>	Set the callback function for an existing key group
<b>setupKeys ()</b>	Setup key handling stream
<b>endKeys (flush)</b>	Cancel keypress handling
<b>writeBotLeft (s)</b>	Write string to Bottom Left of LCD, curBotLeft is set to s
<b>writeBotRight (s)</b>	Write string to Bottom Right of LCD, curBotRight is set to s
<b>setBitsBotAnnuns (d)</b>	Sets the annunciator bits for Bottom Annunciators
<b>clrBitsBotAnnuns (d)</b>	Clears the annunciator bits for Bottom Annunciators
<b>rotWAIT (dir)</b>	Rotate the WAIT annunciator
<b>setBitsTopAnnuns (d)</b>	Sets the annunciator bits for Top Annunciators
<b>clrBitsTopAnnuns (d)</b>	Clears the annunciator bits for Top Annunciators
<b>restoreLcd ()</b>	Called to restore the LCD to its default state
<b>setAnalogType (typ)</b>	Set the analog output type
<b>setAnalogVal (val)</b>	Sets the analogue output to minimum 0.0 through to maximum 1.0
<b>setAnalogPC (val)</b>	Sets the analogue output to minimum 0% through to maximum 100%
<b>setAnalogVolt (val)</b>	Sets the analogue output to minimum 0.0V through to maximum 10.0V
<b>setAnalogCur (val)</b>	Sets the analogue output to minimum 4.0 through to maximum 20.0 mA
<b>turnOn (IO)</b>	Turns IO Output on
<b>turnOff (IO)</b>	Turns IO Output off
<b>enableOutput (IO)</b>	Sets IO Output under LUA control
<b>releaseOutput (IO)</b>	Sets IO Output under instrument control
<b>setpParam (setp, reg, v)</b>	Private function
<b>setpRegAddress (setp, reg)</b>	returns actual register address for a particular setpoint parameter
<b>setpTarget (setp, target)</b>	Set Target for setpoint
<b>setpIO (setp, IO)</b>	Set which Output the setpoint controls
<b>setpType (setp, v)</b>	Set the TYPE of the setpoint controls
<b>setpLogic (setp, v)</b>	Set the Logic for the setpoint controls
<b>setpAlarm (setp, v)</b>	Set the Alarm for the setpoint
<b>setpName (setp, v)</b>	Set the Name of the setpoint
<b>setpSource (setp, v)</b>	Set the data source of the setpoint controls
<b>setpHys (setp, v)</b>	Set the Hysteresis for of the setpoint controls
<b>setNumSetp (n)</b>	Set the number of Setpoints
<b>setBuzzLen (len)</b>	Called to set the length of the buzzer sound
<b>buzz (times)</b>	Called to trigger instrument buzzer
<b>getKey (keyGroup)</b>	Called to get a key from specified key group
<b>edit (prompt, def, typ)</b>	Called to prompt operator to enter a value
<b>sendRegCallback (data, err)</b>	Private function

<code>sendRegWait (cmd, reg, data, t)</code>	Called to send command and wait for response
<code>readRegWait (reg)</code>	Called to read register contents
<code>editRegister (reg)</code>	Called to edit value of specified register
<code>delayCallback ()</code>	Private function
<code>delay (t)</code>	Called to delay for t msec while keeping event handlers running
<code>askOKCallback (key, state)</code>	Private function
<code>askOK (prompt, q)</code>	Prompts operator and waits for OK or CANCEL key press
<code>selectOption (prompt, options, def, loop)</code>	Prompts operator to select from a list of options using arrow keys and KEY_OK
<code>printCustomTransmit (tokenStr, comPort)</code>	Send custom print token string to instrument comms port
<code>reqCustomTransmit (tokenStr)</code>	Called to request response based on custom transmit token string
<code>sendDateFormat (fmt)</code>	sets the instrument date format
<code>RTCread (d)</code>	Read Real Time Clock data from instrument into local RTC table
<code>RTCtick ()</code>	Called every second to update local RTC
<code>RTCtoString ()</code>	Returns formated date/time string Private function
<code>RTCdateFormat (first, second, third)</code>	Sets the order of the date string.byte
<code>tare ()</code>	<>
<code>presetTare ()</code>	<>
<code>gross ()</code>	<>
<code>net ()</code>	<>
<code>grossNetToggle ()</code>	<>

## Fields

<code>fullscale</code>	Called to collect key system data from instrument to configure the local L401 library
<code>s</code>	Control the use of RTC status bit
<code>num</code>	Control the use of reading count status bit.
<code>mask</code>	private function [[function _M.setIOStatus(mask)
<code>curlIOStatus</code>	sets IO status IO bit to recognise this IO
<code>curlIOStatus</code>	sets IO status IO bit to ignore this IO
<code>REG_DISP_LAYOUT</code>	LCD Services LCD display registers
<code>REG_ANALOGUE_DATA</code>	Routines for Analogue Output control
<code>REG_IO_STATUS</code>	Routines for Setpoint Output control
<code>getKeyPressed</code>	Routines for Dialog control
<code>REG_TIMECUR</code>	RTC Routines Time and Date
<code>REG_ADC_TARE</code>	Commands TODO: Finalise these commands to return proper error messages etc [[_M.REG_ADC_ZERO = 0x0300 -- Execute registers

## Functions

### `connect (sock, system)`

Called to connect the L401 library to a socket and a system

#### Parameters:

- `sock`: TCP socket to connect
- `system`: System that manages L401 (nil if stand-alone library)

### `getRegDP (reg)`

Called to read a register value and return value and dp position Used to work out the dp position of a register value so subsequent reads can use the hexadecimal format and convert locally using toFloat

#### Parameters:

- `reg`: register to read

#### Returns:

register value number and dp position

### `saveSetting ()`

Called to save any changed settings and re-initialise instrument

### `toPrimary (v)`

Called to convert a floating point value to a decimal integer based on then primary instrument weighing settings

#### Parameters:

- `v`: is value to convert

#### Returns:

floating point value suitable for a WRFINALDEC

---

**toFloat (data, dp)**

called to convert hexadecimal return string to a floating point number

**Parameters:**

- *data*: returned from \_CMD\_RDFINALHEX or from stream
- *dp*: decimal position

**Returns:**

floating point number

---

**streamCallback (data, err)**

Divide the data stream up and run the relevant callbacks

**Parameters:**

- *data*: Data received from register
- *err*: Potential error message

---

**addStream (streamReg, callback, onChange)**

Add a stream to the device (must be connected) Takes parameter 'change' (default) to run callback only if data received changed, 'always' otherwise

**Parameters:**

- *streamReg*: Register to stream from (\_M.REG\_\*)
- *callback*: Function to bind to streaming register
- *onChange*: Change parameter return streamReg identity

---

**removeStream (streamReg)**

Remove a stream from the device

**Parameters:**

- *streamReg*: Register to be removed(\_M.REG\_\*)

---

**streamCleanup ()**

Called to cleanup any unused streaming

---

**setStreamFreq (freq)**

Set the frequency used for streaming

**Parameters:**

- *freq*: Frequency of streaming (\_M.STM\_FREQ\_\*)

---

**statusCallback (data, err)**

Called when status changes are streamed

**Parameters:**

- *data*: Data on status streamed
- *err*: Potential error message

---

**setStatusCallback (stat, callback)**

Set the callback function for a status bit

**Parameters:**

- *stat*: given in \_M.statBinds
- *callback*: Function to run when there is an event on change in status

---

**setupStatus ()**

Setup status monitoring via a stream

---

**endStatus ()**

Cancel status handling

---

**keyCallback (data, err)**

Called when keys are streamed, send the keys to each group it is bound to in order of priority, until one of them returns true. key states are 'short','long','up' Note: keybind tables should be sorted by priority

**Parameters:**

- *data*: Data on key streamed
- *err*: Potential error message

**setKeyCallback (key, callback)**

Set the callback function for an existing key

**Parameters:**

- *key*: A key given in \_M.keyBinds
- *callback*: Function to run when there is an event on the keygroup

**setKeyGroupCallback (keyGroup, callback)**

Set the callback function for an existing key group

**Parameters:**

- *keyGroup*: A keygroup given in \_M.keyGroup.\*
- *callback*: Function to run when there is an event on the keygroup

**setupKeys ()**

Setup key handling stream

**endKeys (flush)**

Cancel keypress handling

**Parameters:**

- *flush*: Flush the current keypresses that have not yet been handled

**writeBotLeft (s)**

Write string to Bottom Left of LCD, curBotLeft is set to s

**Parameters:**

- *s*: string to display

**writeBotRight (s)**

Write string to Bottom Right of LCD, curBotRight is set to s

**Parameters:**

- *s*: string to display

**setBitsBotAnnuns (d)**

Sets the annunciator bits for Bottom Annunciators

**Parameters:**

- *d*: holds bit locations

**clrBitsBotAnnuns (d)**

Clears the annunciator bits for Bottom Annunciators

**Parameters:**

- *d*: holds bit locations

**rotWAIT (dir)**

Rotate the WAIT annunciator

**Parameters:**

- *dir*: 1 clockwise, -1 anticlockwise 0 no change

**setBitsTopAnnuns (d)**

Sets the annunciator bits for Top Annunciators

**Parameters:**

- *d*: holds bit locations

**clrBitsTopAnnuns (d)**

Clears the annunciator bits for Top Annunciators

**Parameters:**

- *d*: holds bit locations

**restoreLcd ()**

Called to restore the LCD to its default state

**setAnalogType (typ)**

Set the analog output type

**Parameters:**

- *typ*: Type for output (.CUR or .VOLT)

---

**setAnalogVal (val)**

Sets the analogue output to minimum 0.0 through to maximum 1.0

**Parameters:**

- *val*: value 0.0 to 1.0

---

**setAnalogPC (val)**

Sets the analogue output to minimum 0% through to maximum 100%

**Parameters:**

- *val*: value 0 to 100 %

---

**setAnalogVolt (val)**

Sets the analogue output to minimum 0.0V through to maximum 10.0V

**Parameters:**

- *val*: value 0.0 to 10.0

---

**setAnalogCur (val)**

Sets the analogue output to minimum 4.0 through to maximum 20.0 mA

**Parameters:**

- *val*: value 4.0 to 20.0

---

**turnOn (IO)**

Turns IO Output on

**Parameters:**

- *IO* is output 1..32

---

**turnOff (IO)**

Turns IO Output off

**Parameters:**

- *IO* is output 1..32

---

**enableOutput (IO)**

Sets IO Output under LUA control

**Parameters:**

- *IO* is input 1..32

---

**releaseOutput (IO)**

Sets IO Output under instrument control

**Parameters:**

- *IO* is output 1..32

---

**setUpParam (setp, reg, v)**

Private function

**Parameters:**

- *setp*
- *reg*:
- *v*:

---

**setUpRegAddress (setp, reg)**

returns actual register address for a particular setpoint parameter

**Parameters:**

- *setp* is setpoint 1..16
- *reg* is REG\_SETP\_\*

**Returns:**

address of this register for setpoint setp

**setpTarget (setp, target)**

Set Target for setpoint

**Parameters:**

- *setp*: Setpoint 1..16
- *target*: Target value

**setpIO (setp, IO)**

Set which Output the setpoint controls

**Parameters:**

- *setp* is setpoint 1..16
- *IO* is output 1..32, 0 for none

**setpType (setp, v)**

Set the TYPE of the setpoint controls

**Parameters:**

- *setp* is setpoint 1..16
- *v*: setpoint type

**setpLogic (setp, v)**

Set the Logic for the setpoint controls

**Parameters:**

- *setp* is setpoint 1..16
- *v*: setpoint logic type

**setpAlarm (setp, v)**

Set the Alarm for the setpoint

**Parameters:**

- *setp* is setpoint 1..16
- *v*: alarm type

**setpName (setp, v)**

Set the Name of the setpoint

**Parameters:**

- *setp* is setpoint 1..16
- *v*: setpoint name

**setpSource (setp, v)**

Set the data source of the setpoint controls

**Parameters:**

- *setp* is setpoint 1..16
- *v*: setpoint source type

**setpHys (setp, v)**

Set the Hysteresis for of the setpoint controls

**Parameters:**

- *setp* is setpoint 1..16
- *v*: setpoint hysteresis

**setNumSetp (n)**

Set the number of Setpoints

**Parameters:**

- *n*: the number of setpoints 0..16

**setBuzzLen (len)**

Called to set the length of the buzzer sound

**Parameters:**

- *len*: - length of buzzer sound (BUZZ\_SHORT, BUZZ\_MEDIUM, BUZZ\_LONG)

**buzz (times)**

Called to trigger instrument buzzer

**Parameters:**

- *times*: - number of times to buzz, 1..4

**getKey (keyGroup)**

Called to get a key from specified key group

**Parameters:**

- *keyGroup*: keyGroup.all is default group

**Returns:**

key (KEY\_), state ('short','long','up')

**edit (prompt, def, typ)**

Called to prompt operator to enter a value

**Parameters:**

- *prompt*: string displayed on bottom right LCD
- *def*: default value
- *typ*: type of value to enter ('integer','number','string')

**Returns:**

value and true if ok pressed at end

**sendRegCallback (data, err)**

Private function

**Parameters:**

- *data*:
- *err*:

**sendRegWait (cmd, reg, data, t)**

Called to send command and wait for response

**Parameters:**

- *cmd*: CMD\_ command
- *reg*: REG\_ register
- *data*: to send
- *t*: timeout in msec

**Returns:**

1. data received from instrument, nil if error
2. err error string if error received, nil otherwise

**readRegWait (reg)**

Called to read register contents

**Parameters:**

- *reg*: REG\_ register

**Returns:**

1. data received from instrument, nil if error
2. err error string if error received, nil otherwise

**editRegister (reg)**

Called to edit value of specified register

**Parameters:**

- *reg*: is register to edit

**delayCallback ()**

Private function

**delay (t)**

Called to delay for t msec while keeping event handlers running

**Parameters:**

- *t*: delay time in msec

**askOKCallback (key, state)**

Private function

**Parameters:**

- *key*:
- *state*:

**askOK (prompt, q)**

Prompts operator and waits for OK or CANCEL key press

**Parameters:**

- *prompt*: string to put on bottom right LCD
- *q*: string to put on bottom left LCD

**Returns:**

either KEY\_OK or KEY\_CANCEL

**selectOption (prompt, options, def, loop)**

Prompts operator to select from a list of options using arrow keys and KEY\_OK

**Parameters:**

- *prompt*: string to put on bottom right LCD
- *options*: table of option strings
- *def*: default selection string.byte
- *loop*: If true, top option loops to the bottom option and vice versa

**Returns:**

selected string (default selection if KEY\_CANCEL pressed)

**printCustomTransmit (tokenStr, comPort)**

Send custom print token string to instrument comms port

**Parameters:**

- *tokenStr*: string containing custom print tokens
- *comPort*: - port to use PRINT\_SER1A (default) .. PRINT\_SER2B

**reqCustomTransmit (tokenStr)**

Called to request response based on custom transmit token string

**Parameters:**

- *tokenStr*: custom token string

**sendDateFormat (fmt)**

sets the instrument date format

**Parameters:**

- *fmt*: TM\_MMDDYYYY or TM\_DDMMYYYY

**RTCread (d)**

Read Real Time Clock data from instrument into local RTC table

**Parameters:**

- *d*: 'date' or 'time' to read these fields only, or 'all' for both

**RTCtick ()**

Called every second to update local RTC

**RTCtostring ()**

Returns formated date/time string Private function

**RTCdateFormat (first, second, third)**

Sets the order of the date string.byte

**Parameters:**

- *first* = 'day', 'month' or 'year'
- *second* = 'day', 'monht','year'
- *third* = 'day','month','year'

**tare ()**

<>

**presetTare ()**

<>

**gross ()**

<>

**net ()**

<>

**grossNetToggle ()**

<>

## Fields

**fullscale**

Called to collect key system data from instrument to configure the local L401 library

**s**

Control the use of RTC status bit

**num**

Control the use of reading count status bit. This is useful if weight readings are not collected via an on change stream register directly

**mask**

private function [[function \_M.setIOStatus(mask)

**curlIOStatus**

sets IO status IO bit to recognise this IO

**curlIOStatus**

sets IO status IO bit to ignore this IO

**REG\_DISP\_LAYOUT**

LCD Services LCD display registers

**REG\_ANALOGUE\_DATA**

Routines for Analogue Output control

**REG\_IO\_STATUS**

Routines for Setpoint Output control

**getKeyPressed**

Routines for Dialog control

**REG\_TIMECUR**

RTC Routines Time and Date

**REG\_ADC\_TARE**

Commands TODO: Finalise these commands to return proper error messages etc  
[[\_M.REG\_ADC\_ZERO = 0x0300 -- Execute registers

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**Module rinLibrary.L401**

Libary for the L401, providing easy functionality for interfacing with all aspects of the device

**Functions**

<b>connect (sock, system)</b>	Called to connect the L401 library to a socket and a system
<b>getRegDP (reg)</b>	Called to read a register value and return value and dp position Used to work out the dp position of a register value so subsequent reads can use the hexadecimal format and convert locally using toFloat
<b>saveSetting ()</b>	Called to save any changed settings and re-initialise instrument
<b>toPrimary (v)</b>	Called to convert a floating point value to a decimal integer based on then primary instrument weighing settings
<b>toFloat (data, dp)</b>	called to convert hexadecimal return string to a floating point number
<b>streamCallback (data, err)</b>	Divide the data stream up and run the relevant callbacks
<b>addStream (streamReg, callback, onChange)</b>	Add a stream to the device (must be connected) Takes parameter 'change' (default) to run callback only if data received changed, 'always' otherwise
<b>removeStream (streamReg)</b>	Remove a stream from the device
<b>streamCleanup ()</b>	Called to cleanup any unused streaming
<b>setStreamFreq (freq)</b>	Set the frequency used for streaming
<b>statusCallback (data, err)</b>	Called when status changes are streamed
<b>setStatusCallback (stat, callback)</b>	Set the callback function for a status bit
<b>setupStatus ()</b>	Setup status monitoring via a stream
<b>setRTCStatus (s)</b>	Control the use of RTC status bit
<b>setRDGStatus (num)</b>	Control the use of reading count status bit.
<b>setIStatusBar ()</b>	private function
<b>enableIStatusBar (IO)</b>	sets IO status IO bit to recognise this IO
<b>releaseIStatusBar (IO)</b>	sets IO status IO bit to ignore this IO
<b>endStatus ()</b>	Cancel status handling
<b>keyCallback (data, err)</b>	Called when keys are streamed, send the keys to each group it is bound to in order of priority, until one of them returns true.
<b>setKeyCallback (key, callback)</b>	Set the callback function for an existing key
<b>setKeyGroupCallback (keyGroup, callback)</b>	Set the callback function for an existing key group
<b>setupKeys ()</b>	Setup key handling stream
<b>endKeys (flush)</b>	Cancel keypress handling
<b>writeBotLeft (s)</b>	Write string to Bottom Left of LCD, curBotLeft is set to s
<b>writeBotRight (s)</b>	Write string to Bottom Right of LCD, curBotRight is set to s
<b>setBitsBotAnnuns (d)</b>	Sets the annunciator bits for Bottom Annunciators
<b>clrBitsBotAnnuns (d)</b>	Clears the annunciator bits for Bottom Annunciators
<b>rotWAIT (dir)</b>	Rotate the WAIT annunciator
<b>setBitsTopAnnuns (d)</b>	Sets the annunciator bits for Top Annunciators
<b>clrBitsTopAnnuns (d)</b>	Clears the annunciator bits for Top Annunciators
<b>restoreLcd ()</b>	Called to restore the LCD to its default state
<b>setAnalogType (typ)</b>	Set the analog output type
<b>setAnalogVal (val)</b>	Sets the analogue output to minimum 0.0 through to maximum 1.0
<b>setAnalogPC (val)</b>	Sets the analogue output to minimum 0% through to maximum 100%
<b>setAnalogVolt (val)</b>	Sets the analogue output to minimum 0.0V through to maximum 10.0V
<b>setAnalogCur (val)</b>	Sets the analogue output to minimum 4.0 through to maximum 20.0 mA
<b>turnOn (IO)</b>	Turns IO Output on
<b>turnOff (IO)</b>	Turns IO Output off
<b>enableOutput (IO)</b>	Sets IO Output under LUA control
<b>releaseOutput (IO)</b>	Sets IO Output under instrument control
<b>setpParam (setp, reg, v)</b>	Private function
<b>setpRegAddress (setp, reg)</b>	returns actual register address for a particular setpoint parameter
<b>setpTarget (setp, target)</b>	Set Target for setpoint
<b>setpIO (setp, IO)</b>	Set which Output the setpoint controls
<b>setpType (setp, v)</b>	Set the TYPE of the setpoint controls
<b>setpLogic (setp, v)</b>	Set the Logic for the setpoint controls
<b>setpAlarm (setp, v)</b>	Set the Alarm for the setpoint
<b>setpName (setp, v)</b>	Set the Name of the setpoint
<b>setpSource (setp, v)</b>	Set the data source of the setpoint controls
<b>setpHys (setp, v)</b>	Set the Hysteresis for of the setpoint controls
<b>setNumSetp (n)</b>	Set the number of Setpoints

<code>setBuzzLen (len)</code>	Called to set the length of the buzzer sound
<code>buzz (times)</code>	Called to trigger instrument buzzer
<code>getKey (keyGroup)</code>	Called to get a key from specified key group
<code>edit (prompt, def, typ)</code>	Called to prompt operator to enter a value
<code>sendRegCallback (data, err)</code>	Private function
<code>sendRegWait (cmd, reg, data, t)</code>	Called to send command and wait for response
<code>readRegWait (reg)</code>	Called to read register contents
<code>editRegister (reg)</code>	Called to edit value of specified register
<code>delayCallback ()</code>	Private function
<code>delay (t)</code>	Called to delay for t msec while keeping event handlers running
<code>askOKCallback (key, state)</code>	Private function
<code>askOK (prompt, q)</code>	Prompts operator and waits for OK or CANCEL key press
<code>selectOption (prompt, options, def, loop)</code>	Prompts operator to select from a list of options using arrow keys and KEY_OK
<code>printCustomTransmit (tokenStr, comPort)</code>	Send custom print token string to instrument comms port
<code>reqCustomTransmit (tokenStr)</code>	Called to request response based on custom transmit token string
<code>sendDateFormat (fmt)</code>	sets the instrument date format
<code>RTCread (d)</code>	Read Real Time Clock data from instrument into local RTC table
<code>RTCTick ()</code>	Called every second to update local RTC
<code>RTCtostring ()</code>	Returns formated date/time string Private function
<code>RTCdateFormat (first, second, third)</code>	Sets the order of the date string.byte
<code>zero ()</code>	<>
<code>tare ()</code>	<>
<code>presetTare ()</code>	<>
<code>gross ()</code>	<>
<code>net ()</code>	<>
<code>grossNetToggle ()</code>	<>

## Fields

<code>fullscale</code>	Called to collect key system data from instrument to configure the local L401 library
<code>REG_DISP_LAYOUT</code>	LCD Services LCD display registers
<code>REG_ANALOGUE_DATA</code>	Routines for Analogue Output control
<code>REG_IO_STATUS</code>	Routines for Setpoint Output control
<code>getKeyPressed</code>	Routines for Dialog control
<code>REG_TIMECUR</code>	RTC Routines Time and Date
<code>REG_ADC_ZERO</code>	Commands TODO: Finalise these commands to return proper error messages etc

## Functions

### `connect (sock, system)`

Called to connect the L401 library to a socket and a system

#### Parameters:

- `sock`: TCP socket to connect
- `system`: System that manages L401 (nil if stand-alone library)

### `getRegDP (reg)`

Called to read a register value and return value and dp position Used to work out the dp position of a register value so subsequent reads can use the hexadecimal format and convert locally using toFloat

#### Parameters:

- `reg`: register to read

#### Returns:

register value number and dp position

### `saveSetting ()`

Called to save any changed settings and re-initialise instrument

### `toPrimary(v)`

Called to convert a floating point value to a decimal integer based on then primary instrument weighing settings

#### Parameters:

- `v`: value to convert

**Returns:**

floating point value suitable for a WRFINALDEC

**toFloat (data, dp)**

called to convert hexadecimal return string to a floating point number

**Parameters:**

- *data*: returned from \_CMD\_RDFINALHEX or from stream
- *dp*: decimal position

**Returns:**

floating point number

**streamCallback (data, err)**

Divide the data stream up and run the relevant callbacks

**Parameters:**

- *data*: Data received from register
- *err*: Potential error message

**addStream (streamReg, callback, onChange)**

Add a stream to the device (must be connected) Takes parameter 'change' (default) to run callback only if data received changed, 'always' otherwise

**Parameters:**

- *streamReg*: Register to stream from (\_M.REG\_\*)
- *callback*: Function to bind to streaming register
- *onChange*: Change parameter return streamReg identity

**removeStream (streamReg)**

Remove a stream from the device

**Parameters:**

- *streamReg*: Register to be removed(\_M.REG\_\*)

**streamCleanup ()**

Called to cleanup any unused streaming

**setStreamFreq (freq)**

Set the frequency used for streaming

**Parameters:**

- *freq*: Frequency of streaming (\_M.STM\_FREQ\_\*)

**statusCallback (data, err)**

Called when status changes are streamed

**Parameters:**

- *data*: Data on status streamed
- *err*: Potential error message

**setStatusCallback (stat, callback)**

Set the callback function for a status bit

**Parameters:**

- *stat*: given in \_M.statBinds
- *callback*: Function to run when there is an event on change in status

**setupStatus ()**

Setup status monitoring via a stream

**setRTCStatus (s)**

Control the use of RTC status bit

**Parameters:**

- *s*: true to enable RTC change monitoring, false to disable

**setRDGStatus (num)**

Control the use of reading count status bit. This is useful if weight readings are not collected via an on change stream register directly

**Parameters:**

- *num*: Sets amount of readings to trigger a reading count status change

**setIOStatus ()**

private function

**enableIOStatus (IO)**

sets IO status IO bit to recognise this IO

**Parameters:**

- *IO*: is output 1..32

**releaseIOStatus (IO)**

sets IO status IO bit to ignore this IO

**Parameters:**

- *IO*: is output 1..32

**endStatus ()**

Cancel status handling

**keyCallback (data, err)**

Called when keys are streamed, send the keys to each group it is bound to in order of priority, until one of them returns true. key states are 'short','long','up' Note: keybind tables should be sorted by priority

**Parameters:**

- *data*: Data on key streamed
- *err*: Potential error message

**setKeyCallback (key, callback)**

Set the callback function for an existing key

**Parameters:**

- *key*: A key given in \_M.keyBinds
- *callback*: Function to run when there is an event on the keygroup

**setKeyGroupCallback (keyGroup, callback)**

Set the callback function for an existing key group

**Parameters:**

- *keyGroup*: A keygroup given in \_M.keyGroup.\*
- *callback*: Function to run when there is an event on the keygroup

**setupKeys ()**

Setup key handling stream

**endKeys (flush)**

Cancel keypress handling

**Parameters:**

- *flush*: Flush the current keypresses that have not yet been handled

**writeBotLeft (s)**

Write string to Bottom Left of LCD, curBotLeft is set to s

**Parameters:**

- *s*: string to display

**writeBotRight (s)**

Write string to Bottom Right of LCD, curBotRight is set to s

**Parameters:**

- *s*: string to display

**setBitsBotAnnuns (d)**

Sets the annunciator bits for Bottom Announciators

**Parameters:**

- *d*: holds bit locations

**clrBitsBotAnnuns (d)**

Clears the annunciator bits for Bottom Annunciators

**Parameters:**

- *d*: holds bit locations

**rotWAIT (dir)**

Rotate the WAIT annunciator

**Parameters:**

- *dir*: 1 clockwise, -1 anticlockwise 0 no change

**setBitsTopAnnuns (d)**

Sets the annunciator bits for Top Annunciators

**Parameters:**

- *d*: holds bit locations

**clrBitsTopAnnuns (d)**

Clears the annunciator bits for Top Annunciators

**Parameters:**

- *d*: holds bit locations

**restoreLcd ()**

Called to restore the LCD to its default state

**setAnalogType (typ)**

Set the analog output type

**Parameters:**

- *typ*: Type for output (.CUR or .VOLT)

**setAnalogVal (val)**

Sets the analogue output to minimum 0.0 through to maximum 1.0

**Parameters:**

- *val*: value 0.0 to 1.0

**setAnalogPC (val)**

Sets the analogue output to minimum 0% through to maximum 100%

**Parameters:**

- *val*: value 0 to 100 %

**setAnalogVolt (val)**

Sets the analogue output to minimum 0.0V through to maximum 10.0V

**Parameters:**

- *val*: value 0.0 to 10.0

**setAnalogCur (val)**

Sets the analogue output to minimum 4.0 through to maximum 20.0 mA

**Parameters:**

- *val*: value 4.0 to 20.0

**turnOn (IO)**

Turns IO Output on

**Parameters:**

- *IO*: is output 1..32

**turnOff (IO)**

Turns IO Output off

**Parameters:**

- *IO*: is output 1..32

**enableOutput (IO)**

Sets IO Output under LUA control

**Parameters:**

- *IO* is input 1..32

**releaseOutput (IO)**

Sets IO Output under instrument control

**Parameters:**

- *IO* is output 1..32

**setParam (setp, reg, v)**

Private function

**Parameters:**

- *setp*
- *reg*:
- *v*:

**setRegAddress (setp, reg)**

returns actual register address for a particular setpoint parameter

**Parameters:**

- *setp* is setpoint 1..16
- *reg*: is REG\_SETP\_\*

**Returns:**

address of this registet for setpoint setp

**setTarget (setp, target)**

Set Target for setpoint

**Parameters:**

- *setp*: Setpoint 1..16
- *target*: Target value

**setpIO (setp, IO)**

Set which Output the setpoint controls

**Parameters:**

- *setp* is setpoint 1..16
- *IO* is output 1..32, 0 for none

**setpType (setp, v)**

Set the TYPE of the setpoint controls

**Parameters:**

- *setp* is setpoint 1..16
- *v*: is setpoint type

**setpLogic (setp, v)**

Set the Logic for the setpoint controls

**Parameters:**

- *setp* is setpoint 1..16
- *v*: is setpoint logic type

**setpAlarm (setp, v)**

Set the Alarm for the setpoint

**Parameters:**

- *setp* is setpoint 1..16
- *v*: alarm type

**setpName (setp, v)**

Set the Name of the setpoint

**Parameters:**

- *setp* is setpoint 1..16

- *v*: is setpoint name

---

**setSource (setp, v)**

Set the data source of the setpoint controls

**Parameters:**

- *setp*: is setpoint 1..16
- *v*: is setpoint source type

---

**setHys (setp, v)**

Set the Hysteresis for of the setpoint controls

**Parameters:**

- *setp*: is setpoint 1..16
- *v*: is setpoint hysteresis

---

**setNumSetp (n)**

Set the number of Setpoints

**Parameters:**

- *n*: is the number of setpoints 0..16

---

**setBuzzLen (len)**

Called to set the length of the buzzer sound

**Parameters:**

- *len*: - length of buzzer sound (BUZZ\_SHORT, BUZZ\_MEDIUM, BUZZ\_LONG)

---

**buzz (times)**

Called to trigger instrument buzzer

**Parameters:**

- *times*: - number of times to buzz, 1..4

---

**getKey (keyGroup)**

Called to get a key from specified key group

**Parameters:**

- *keyGroup*: keyGroup.all is default group

**Returns:**

key (KEY\_), state ('short','long','up')

---

**edit (prompt, def, typ)**

Called to prompt operator to enter a value

**Parameters:**

- *prompt*: string displayed on bottom right LCD
- *def*: default value
- *typ*: type of value to enter ('integer','number','string')

**Returns:**

value and true if ok pressed at end

---

**sendRegCallback (data, err)**

Private function

**Parameters:**

- *data*:
- *err*:

---

**sendRegWait (cmd, reg, data, t)**

Called to send command and wait for response

**Parameters:**

- *cmd*: CMD\_ command
- *reg*: REG\_ register
- *data*: to send
- *t*: timeout in msec

**Returns:**

1. data received from instrument, nil if error

- 
2. err error string if error received, nil otherwise

**readRegWait (reg)**

Called to read register contents

**Parameters:**

- *reg*: REG\_register

**Returns:**

1. data received from instrument, nil if error
  2. err error string if error received, nil otherwise
- 

**editRegister (reg)**

Called to edit value of specified register

**Parameters:**

- *reg*: is register to edit
- 

**delayCallback ()**

Private function

---

**delay (t)**

Called to delay for t msec while keeping event handlers running

**Parameters:**

- *t*: delay time in msec
- 

**askOKCallback (key, state)**

Private function

**Parameters:**

- *key*:
  - *state*:
- 

**askOK (prompt, q)**

Prompts operator and waits for OK or CANCEL key press

**Parameters:**

- *prompt*: string to put on bottom right LCD
- *q*: string to put on bottom left LCD

**Returns:**

either KEY\_OK or KEY\_CANCEL

---

**selectOption (prompt, options, def, loop)**

Prompts operator to select from a list of options using arrow keys and KEY\_OK

**Parameters:**

- *prompt*: string to put on bottom right LCD
- *options*: table of option strings
- *def*: default selection string,byte
- *loop*: If true, top option loops to the bottom option and vice versa

**Returns:**

selected string (default selection if KEY\_CANCEL pressed)

---

**printCustomTransmit (tokenStr, comPort)**

Send custom print token string to instrument comms port

**Parameters:**

- *tokenStr*: string containing custom print tokens
  - *comPort*: - port to use PRINT\_SER1A (default) .. PRINT\_SER2B
- 

**reqCustomTransmit (tokenStr)**

Called to request response based on custom transmit token string

**Parameters:**

- *tokenStr*: custom token string
- 

**sendDateFormat (fmt)**

sets the instrument date format

**Parameters:**

- *fmt*: TM\_MMDDYYYY or TM\_DDMMYYYY

**RTCread (d)**

Read Real Time Clock data from instrument into local RTC table

**Parameters:**

- *d*: 'date' or 'time' to read these fields only, or 'all' for both

**RTCtick ()**

Called every second to update local RTC

**RTCtostring ()**

Returns formated date/time string Private function

**RTCdateFormat (first, second, third)**

Sets the order of the date string.byte

**Parameters:**

- *first* = 'day', 'month' or 'year'
- *second* = 'day', 'monht','year'
- *third* = 'day','month','year'

**zero ()**

<>

**tare ()**

<>

**presetTare ()**

<>

**gross ()**

<>

**net ()**

<>

**grossNetToggle ()**

<>

**Fields****fullscale**

Called to collect key system data from instrument to configure the local L401 library

**REG\_DISP\_LAYOUT**

LCD Services LCD display registers

**REG\_ANALOGUE\_DATA**

Routines for Analogue Output control

**REG\_IO\_STATUS**

Routines for Setpoint Output control

**getKeyPressed**

Routines for Dialog control

**REG\_TIMECUR**

RTC Routines Time and Date

**REG\_ADC\_ZERO**

Commands TODO: Finalise these commands to return proper error messages etc

generated by **LDoc 1.2**

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Documentation of the Idoc features

**Section Comments**

<b>tableName</b>	Table Definition.
<b>myFunction (p1, p2)</b>	General Function Description goes here.
<b>anotherFunction (p1, p2)</b>	Another Function Description goes here.
<b>localFunction</b>	Private Method You need -a flag or 'all=true' to see these

**Section Comments**

Description of the section goes here

**tableName**

Table Definition.

**Fields:**

- *FIELD1*: Field 1 Description
- *FIELD2*: Field 2 DescriptionREG\_SOFTVER Software Version eg "V1.00"
- *FIELD3*: Field 3 DescriptionREG\_SERIALNO Serial Number

**myFunction (p1, p2)**

General Function Description goes here.

**Parameters:**

- *p1*: Parameter 1 description
- *p2*: Parameter 2 description

**Usage:**

```
a = myFunction(1,2) -- comment in example code
```

**Returns:**

return description

**see also:**[anotherFunction](#)**anotherFunction (p1, p2)**

Another Function Description goes here. You can add multiple lines of description and link to standard Lua functions also.

**Parameters:**

- *p1*: Parameter 1 description
- *p2*: Parameter 2 description

**Usage:**

```
b = anotherFunction(1,2) -- comment in example code
```

**Returns:**

returns description

**see also:**[string.sub](#)**localFunction**

Private Method You need -a flag or 'all=true' to see these

**Parameters:**

- *p1*:
- *p2*:

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**Module rinLibrary.rinCSV**

Functions for working .CSV files and creating multi-table databases

**CSV Utilities**

<a href="#">escapeCSV (s)</a>	Adds "" around s if it contains ',' or "" and replaces "" with """
<a href="#">toCSV (t)</a>	Converts a table (1d array) to a CSV string with fields escaped if required
<a href="#">padCSV (t, w)</a>	Converts a table (1d array) to a CSV string with fields escaped if required
<a href="#">fromCSV (s)</a>	Takes an escaped CSV string and returns a line (1d array)
<a href="#">equalCSV (labels, check)</a>	Checks labels to ensure database table is the same structure Tolerant of additional whitespace in labels and ignores case

**CSV Functions**

<a href="#">saveCSV (t)</a>	Save table t to a .CSV file
<a href="#">loadCSV (t)</a>	Reads a .CSV file and returns a table with the loaded contents If no CSV file found or contents different then file created with structure in t
<a href="#">logLineCSV (t, line)</a>	Adds line of data to a CSV file but does not update local data in table
<a href="#">addLineCSV (t, line)</a>	Adds line of data to a table
<a href="#">dupLineCSV (line)</a>	Makes a duplicate copy of a line of data
<a href="#">remLineCSV (t, row)</a>	Removes line of data in a table (does not save .CSV file)
<a href="#">getLineCSV (t, val, col)</a>	Removes line of data in a table (does not save .CSV file)
<a href="#">replaceLineCSV (t, row, line)</a>	Replaces a line of data in the table (does not save the .CSV file)
<a href="#">labelCol (t, label)</a>	Returns the column number of a particular label
<a href="#">tostringCSV (t, w)</a>	Converts contents of the CSV table into a print friendly string

**Database Utilities**

<a href="#">addTableDB (db, name, t)</a>	Adds a database table to the database, updates contents with t if already present
<a href="#">loadDB (db)</a>	Restores database contents from CSV files Only loads in database tables already registered with database
<a href="#">addLineDB (db, name, l)</a>	Adds line of data to a table in the database
<a href="#">remLineDB (db, name, line)</a>	Removes last line of data in a database table
<a href="#">saveDB (db)</a>	Save database to multiple CSV files
<a href="#">tostringDB (db, w)</a>	Converts contents of the database into a print friendly string

**CSV Utilities**

Functions to convert data to and from .CSV format

**escapeCSV(s)**

Adds "" around s if it contains ',' or "" and replaces "" with """

**Parameters:**

- *s*: string to escape

**Returns:**

escaped string

**toCSV(t)**

Converts a table (1d array) to a CSV string with fields escaped if required

**Parameters:**

- *t*: table to convert

**Returns:**

escaped CSV string

**padCSV(t, w)**

Converts a table (1d array) to a CSV string with fields escaped if required

**Parameters:**

- *t*: table to convert
- *w*: width of each cell

**Returns:**

escaped CSV string padded to w characters in each cell

**fromCSV(s)**

Takes an escaped CSV string and returns a line (1d array)

**Parameters:**

- *s*: CSV string

**Returns:**

table (1d array)

**equalCSV (labels, check)**

Checks labels to ensure database table is the same structure Tolerant of additional whitespace in labels and ignores case

**Parameters:**

- *labels*: 1d array of labels from a database table
- *check*: 1d array of labels to check

**Returns:**

true if labels and check are the same, false otherwise

## CSV Functions

Functions to manage CSV files directly

**saveCSV (t)**

Save table t to a .CSV file

**Parameters:**

- *t*: database table to save. table is in the format: fname name of .csv file associated with table - used to save/restore table contents labels[] 1d array of column labels data[][] 2d array of data

**Returns:**

table in same format:

**loadCSV (t)**

Reads a .CSV file and returns a table with the loaded contents If no CSV file found or contents different then file created with structure in t

**Parameters:**

- *t*: is table with structure of expected CSV included

**Returns:**

table in same format: fname name of .csv file associated with table - used to save/restore table contents labels[] 1d array of column labels data[][] 2d array of data

**logLineCSV (t, line)**

Adds line of data to a CSV file but does not update local data in table

**Parameters:**

- *t*: is table describing CSV data
- *line*: is a row of data (1d array) to save

**addLineCSV (t, line)**

Adds line of data to a table

**Parameters:**

- *t*: is table holding CSV data
- *line*: of data (1d array) to add to the table

**Returns:**

row location of line new line in table

**dupLineCSV (line)**

Makes a duplicate copy of a line of data

**Parameters:**

- *line*: is the line of data (1-d array)

**Returns:**

duplicate copy of line

**remLineCSV (t, row)**

Removes line of data in a table (does not save .CSV file)

**Parameters:**

- *t*: is table holding CSV data
- *row*: is row number of table data 1..n to remove. removes last line of data if row is nil

**getLineCSV (t, val, col)**

Removes line of data in a table (does not save .CSV file)

**Parameters:**

- *t*: is table holding CSV data
- *val*: is value of the cell to find
- *col*: is the column of data to match (default is col 1)

**Returns:**

1. row that val found in or nil if not found
2. line of data found at that row with matching val data in column col

**replaceLineCSV (t, row, line)**

Replaces a line of data in the table (does not save the .CSV file)

**Parameters:**

- *t*: is table holding CSV data
- *row*: is the row number of the line of data
- *line*: is the line of data

**labelCol (t, label)**

Returns the column number of a particular label

**Parameters:**

- *t*: is table holding CSV data
- *label*: is name of column to find (not case sensitive)

**Returns:**

column number of the label or nil if not found

**toStringCSV (t, w)**

Converts contents of the CSV table into a print friendly string

**Parameters:**

- *t*: table to convert
- *w*: width to pad each cell to

## Database Utilities

Functions to manage multiple tables in a database

**addTableDB (db, name, t)**

Adds a database table to the database, updates contents with *t* if already present

**Parameters:**

- *db*: is the database table to populate
- *name*: is the name of table
- *t*: is the csv table to add database table is in the format fname name of .csv file associated with table
  - used to save/restore table contents labels{} 1d array of column labels data{}{} 2d array of data

**loadDB (db)**

Restores database contents from CSV files Only loads in database tables already registered with database

**Parameters:**

- *db*: database table to populate

**addLineDB (db, name, l)**

Adds line of data to a table in the database

**Parameters:**

- *db*: database table
- *name*: name of table in database to use
- *l*: line (1d array) of data to save

**remLineDB (db, name, line)**

Removes last line of data in a database table

**Parameters:**

- *db*: database table
- *name*: name of table to use
- *line*: is row number of table data 1..n to remove. removes last line if line is nil

**saveDB (db)**

Save database to multiple CSV files

**Parameters:**

- *db*: database table

---

**tostringDB (db, w)**

Converts contents of the database into a print friendly string

**Parameters:**

- *db*: database table
- *w*: width of each cell

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Offer functions for converting variables into strings for debugging

**Functions**

<b>setLevel (level)</b>	Set Debug level
<b>restoreLevel ()</b>	Restores Debug level to previous setting
<b>configureDebug (config, ip)</b>	Configures the level for debugging
<b>getDebugConfig ()</b>	returns debug configuration
<b>tableString (t)</b>	Converts table t into a string
<b>varString (arg)</b>	Converts arg into a string
<b>print (prompt, ...)</b>	Prints variable contents to debugger at current debug level with optional prompt
<b>debug (prompt, ...)</b>	Prints variable contents to debugger at DEBUG level with optional prompt
<b>info (prompt, ...)</b>	Prints variable contents to debugger at INFO level with optional prompt
<b>warn (prompt, ...)</b>	Prints variable contents to debugger at WARN level with optional prompt
<b>error (prompt, ...)</b>	Prints variable contents to debugger at ERROR level with optional prompt
<b>fatal (prompt, ...)</b>	Prints variable contents to debugger at FATAL level with optional prompt
<b>printVar (prompt, v, level)</b>	Prints variable v contents to stdio with optional prompt included for backward compatibility - replaced by print

**Functions****setLevel (level)**

Set Debug level

**Parameters:**

- *level*: enumerated level constant or matching string. If no match level set to INFO

**restoreLevel ()**

Restores Debug level to previous setting

**configureDebug (config, ip)**

Configures the level for debugging

**Parameters:**

- *config*: is table of settings
- *ip*: optional tag printed with each message (usually IP address of the instrument)

**Usage:**

```
dbg.configureDebug({level = 'DEBUG', timestamp = true, logger = 'console'}, 'testDebug')
```

**getDebugConfig ()**

returns debug configuration

**Returns:**

1. level lualogging level
2. timestamp: true if timestamp logging is to included
3. ip

**tableString (t)**

Converts table t into a string

**Parameters:**

- *t*: is a table

**varString (arg)**

Converts arg into a string

**Parameters:**

- *arg*: is any variable

**print (prompt, ...)**

Prints variable contents to debugger at current debug level with optional prompt

**Parameters:**

- *prompt*: is an optional prompt printed before the arguments
- ...: arguments to be printed

**debug (prompt, ...)**

Prints variable contents to debugger at DEBUG level with optional prompt

**Parameters:**

- *prompt*: is an optional prompt printed before the arguments
- ....: arguments to be printed

---

**info (prompt, ...)**

Prints variable contents to debugger at INFO level with optional prompt

**Parameters:**

- *prompt*: is an optional prompt printed before the arguments
- ....: arguments to be printed

---

**warn (prompt, ...)**

Prints variable contents to debugger at WARN level with optional prompt

**Parameters:**

- *prompt*: is an optional prompt printed before the arguments
- ....: arguments to be printed

---

**error (prompt, ...)**

Prints variable contents to debugger at ERROR level with optional prompt

**Parameters:**

- *prompt*: is an optional prompt printed before the arguments
- ....: arguments to be printed

---

**fatal (prompt, ...)**

Prints variable contents to debugger at FATAL level with optional prompt

**Parameters:**

- *prompt*: is an optional prompt printed before the arguments
- ....: arguments to be printed

---

**printVar (prompt, v, level)**

Prints variable v contents to stdio with optional prompt included for backward compatibility - replaced by print

**Parameters:**

- *prompt*: is an optional prompt
- *v*: is a variable whose contents are to be printed
- *level*: is the debug level for the message INFO by default

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# Idoc

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## Module rinLibrary.rinINI

Services for saving and restoring settings in a table to .INI config file

### Functions

<b>saveINI (fname, t)</b>	Saves table t as a .INI name (fname)
<b>loadINI (fname, def)</b>	populates table t with contents of INI file fname if fname is not found a new file is created with table def contents
<b>stringINI (t)</b>	returns table t contents in an INI format string

### Functions

#### saveINI (fname, t)

Saves table t as a .INI name (fname)

##### Parameters:

- *fname*: name of file
- *t*: is table of settings

##### Returns:

*t* if successful, nil otherwise

#### loadINI (fname, def)

populates table t with contents of INI file fname if fname is not found a new file is created with table def contents

##### Parameters:

- *fname*: name of file
- *def*: default table of settings

##### Returns:

table *t* or nil if file invalid

#### stringINI (t)

returns table t contents in an INI format string

##### Parameters:

- *t*: is table of settings

##### Returns:

A string in INI format

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Creates a connection to the M4223

**Functions**[load \(filename, ip, port\)](#)

Read a RIS file and send valid commands to the device

**Functions**[load \(filename, ip, port\)](#)

Read a RIS file and send valid commands to the device

**Parameters:**

- *filename*: Name of the RIS file
- *ip*: IP Address to transmit file contents to
- *port*: Port to transmit file contents to

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Functions for working with VT100 terminal interface

**Functions**

<a href="#">set (s)</a>	Send an escape sequence to the terminal
<a href="#">csrHome ()</a>	Move Cursor to top left of screen
<a href="#">csrXY (x, y)</a>	Move Cursor to position x,y on screen
<a href="#">csrUp (r)</a>	Move Cursor up relative to current position
<a href="#">csrDown (r)</a>	Move Cursor down relative to current position
<a href="#">csrLeft (c)</a>	Move Cursor left relative to current position
<a href="#">csrRight (c)</a>	Move Cursor right relative to current position
<a href="#">csrSave ()</a>	Save current cursor position
<a href="#">csrRestore ()</a>	Restore cursor to saved position
<a href="#">clrScreen ()</a>	Clear terminal screen
<a href="#">clrEol ()</a>	Clear to end of line from cursor position
<a href="#">clrSol ()</a>	Clear to start of line from cursor position
<a href="#">clrRow ()</a>	Clear current row
<a href="#">clrAbove ()</a>	Clear all lines above current cursor position
<a href="#">clrBelow ()</a>	Clear all lines below current cursor position
<a href="#">clrAttr ()</a>	Clear terminal attributes to default settings
<a href="#">scrollAll ()</a>	set terminal to scroll entire screen
<a href="#">scrollSet (r1, r2)</a>	set terminal to scroll only a section of the screen
<a href="#">setAttr (fg, bg)</a>	set terminal attributes
<a href="#">restoreAttr ()</a>	restores last terminal attributes

**Functions****set (s)**

Send an escape sequence to the terminal

**Parameters:**

- *s*: string containing escape sequence to send

**Usage:**

```
VT100 = require rinLibrary.rinVT100

VT100.set(VT100.csrHome()..VT100.setAttr(VT100.FGRed,VT100.BGBlack)

print('Hello'..VT100.csrLeft(10)..'There')
```

**csrHome ()**

Move Cursor to top left of screen

**csrXY (x, y)**

Move Cursor to position x,y on screen

**Parameters:**

- *x*: horizontal position from left, 0 (default) is start
- *y*: vertical position from top, 0 (default) is top of screen

**csrUp (r)**

Move Cursor up relative to current position

**Parameters:**

- *r*: is number of rows to move

**csrDown (r)**

Move Cursor down relative to current position

**Parameters:**

- *r*: is number of rows to move

**csrLeft (c)**

Move Cursor left relative to current position

**Parameters:**

- *c*: is number of columns to move

**csrRight (c)**

Move Cursor right relative to current position

**Parameters:**

- *c*: is number of columns to move

**csrSave ()**

Save current cursor position

**csrRestore ()**

Restore cursor to saved position

**clrScreen ()**

Clear terminal screen

**clrEol ()**

Clear to end of line from cursor position

**clrSol ()**

Clear to start of line from cursor position

**clrRow ()**

Clear current row

**clrAbove ()**

Clear all lines above current cursor position

**clrBelow ()**

Clear all lines below current cursor position

**clrAttr ()**

Clear terminal attributes to default settings

**scrollAll ()**

set terminal to scroll entire screen

**scrollSet (r1, r2)**

set terminal to scroll only a section of the screen

**Parameters:**

- *r1*: row to start scrolling area
- *r2*: row to end scrolling area

**setAttr (fg, bg)**

set terminal attributes

**Parameters:**

- *fg*: foreground colours FG\*
- *bg*: background colours BG\*

**restoreAttr ()**

restores last terminal attributes

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**Module rinLibrary.rincon**

Creates a connection to the M4223

**Functions**

<b>defaultErrorHandler (addr, cmd, reg, data, s)</b>	Default Error Handler, logs error to debug at WARN level with error string and received command takes arguments: Address, Command, Register, Data, Err String from message processing
<b>setErrorHandler (errHandler)</b>	Set your own routine to handle errors reported from the instrument
<b>removeErrorHandler ()</b>	Removes the error handler
<b>socketACallback ()</b>	Designed to be registered with rinSystem.
<b>pushQ (msg)</b>	Add 1 to the queue and put the message on the end of the queue
<b>popQ ()</b>	Remove the message from the front of the queue, and return the message
<b>Qempty ()</b>	Check if the queue is empty
<b>sendQueueCallback ()</b>	Designed to be registered with rinSystem.
<b>disconnect ()</b>	Disconnect from the R400
<b>recMsg ()</b>	Receive a rinCMD message from a socket linked to SERA.
<b>CCITT (data)</b>	Creates a CRC-CCITT (0xFFFF) of the given ASCII data
<b>processMsg (msg, err)</b>	Processes the message and feeds back the individual parts
<b>sendRaw (raw)</b>	Sends a raw message
<b>sendMsg (msg, crc)</b>	Sends a message with delimiters added optionally with CRC
<b>send (addr, cmd, reg, data, reply, crc)</b>	Sends a structured message built up from individual parameters as follows
<b>preconfigureMsg (reg, cmd, reply, crc)</b>	Return a function allowing for repeatable commands
<b>bindRegister (reg, callback)</b>	Set up a callback for when data on a specific register is received
<b>unbindRegister (reg)</b>	Unbind a register
<b>socketBCallback ()</b>	Designed to be registered with rinSystem.
<b>setDelimiters (start, end1, end2)</b>	Set delimiters for messages received from the socket linked to SERB E.g.
<b>setSerBCallback (f)</b>	Set delimiters for messages received from the socket linked to SERB E.g.

**Tables**

<b>rinCMD</b>	Instrument Commands.
---------------	----------------------

**Functions****defaultErrorHandler (addr, cmd, reg, data, s)**

Default Error Handler, logs error to debug at WARN level with error string and received command takes arguments: Address, Command, Register, Data, Err String from message processing

**Parameters:**

- *addr*:
- *cmd*:
- *reg*:
- *data*:
- *s*:

**setErrorHandler (errHandler)**

Set your own routine to handle errors reported from the instrument

**Parameters:**

- *errHandler*: Function for handling errors, should take arguments: Address, Command, Register, Data, Err String.

**removeErrorHandler ()**

Removes the error handler

**Returns:**

original registered handler

**socketACallback ()**

Designed to be registered with rinSystem. If a message error occurs, pass it to the error handler.

**pushQ (msg)**

Add 1 to the queue and put the message on the end of the queue

**Parameters:**

- *msg*: Message to add to the end of the queue

**popQ ()**

Remove the message from the front of the queue, and return the message

**Returns:**

Message removed from the queue

**Qempty ()**

Check if the queue is empty

**Returns:**

True if empty, false otherwise

**sendQueueCallback ()**

Designed to be registered with rinSystem. If a message error occurs, pass it to the error handler.

**disconnect ()**

Disconnect from the R400

**recMsg ()**

Receive a rinCMD message from a socket linked to SERA. Receives one byte at a time, and ends the message based on specified delimiters

**Returns:**

1. A string bounded by delimiters (nil if error)
2. An error message (nil if no error)

**CCITT (data)**

Creates a CRC-CCITT (0xFFFF) of the given ASCII data

**Parameters:**

- *data*: Data to be processed

**Returns:**

CRC-CCITT (0xFFFF) of message This code is relatively slow. Further speed gains will require a switch to C which should bump the speed a thousand fold.

**processMsg (msg, err)**

Processes the message and feeds back the individual parts

**Parameters:**

- *msg*: Message to be processed
- *err*: Error in receive (nil if none)

**Returns:**

1. address (0x00 to 0x1F)
2. command (CMD\_\*)
3. register (REG\_\*)
4. data
5. error

**sendRaw (raw)**

Sends a raw message

**Parameters:**

- *raw*: string to send

**sendMsg (msg, crc)**

Sends a message with delimiters added optionally with CRC

**Parameters:**

- *msg*: message string to send
- *crc*: if crc = 'crc' then SOH msg CRC EOT sent, msg CRLF otherwise (default)

**send (addr, cmd, reg, data, reply, crc)**

Sends a structured message built up from individual parameters as follows

**Parameters:**

- *addr*: Indicator address (0x00 to 0x1F)
- *cmd*: Command (CMD\_\*)

- *reg*: Register (REG\_\*)
- *data*: Data to be sent
- *reply*: - 'reply' (default) if reply required, sent with ADDR\_NOREPLY otherwise
- *crc*: - 'crc' if message sent with crc, false (default) otherwise

---

#### **preconfigureMsg (reg, cmd, reply, crc)**

Return a function allowing for repeatable commands

**Parameters:**

- *reg*: register (REG\_\*)
- *cmd*: command (CMD\_\*)
- *reply*: - 'reply' (default) if reply required, sent with ADDR\_NOREPLY otherwise
- *crc*: - 'crc' if message sent with crc, false (default) otherwise

**Returns:**

preconfigured function

---

#### **bindRegister (reg, callback)**

Set up a callback for when data on a specific register is received

**Parameters:**

- *reg*: Register to give callback, (REG\_\*), 0 is used to match anything received that has no other binding
- *callback*: Function to be run when data is received

---

#### **unbindRegister (reg)**

Unbind a register

**Parameters:**

- *reg*: Register to remove callback, (REG\_\*)

---

#### **socketBCallback ()**

Designed to be registered with rinSystem.

---

#### **setDelimiters (start, end1, end2)**

Set delimiters for messages received from the socket linked to SERB E.g. for \r\n delimiting use parameters: nil, '\r', '\n'

**Parameters:**

- *start*: start character, nil if not used
- *end1*: first end character, nil if not used
- *end2*: second end character, nil if not used

---

#### **setSerBCallback (f)**

Set delimiters for messages received from the socket linked to SERB E.g. for \r\n delimiting use parameters: nil, '\r', '\n'

**Parameters:**

- *f*: callback function that takes a message string as an argument

---

## **Tables**

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### **rinCMD**

Instrument Commands.

**Fields:**

- *CMD\_RDTYPE*: Read Register Type
- *CMD\_RDRANGEMIN*: Read data range minimum
- *CMD\_RDRANGEMAX*: Read data range maximum
- *CMD\_RDRAW*: Read Raw data
- *CMD\_RDLIT*: Read literal data
- *CMD\_WRAW*: Write Raw data
- *CMD\_RDDEFAULT*: Read default setting
- *CMD\_RDNAME*: Read Name
- *CMD\_RDITEM*: Read Item from item list
- *CMD\_RDPERMISSION*: Read register permissions
- *CMD\_RDFINALHEX*: Read data in hexadecimal format
- *CMD\_RDFINALDEC*: Read data in decimal format
- *CMD\_WRFINALHEX*: Write data in hexadecimal format
- *CMD\_WRFINALDEC*: Write data in decimal format
- *CMD\_EX*: Execute with data as execute parameter

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Framework for interfacing with the L401 for advanced applications

**Functions**[handleEvents \(\)](#)

Main function for handling events Issues a callback to any connection or timer that has an event on it.

**Functions**[handleEvents \(\)](#)

Main function for handling events Issues a callback to any connection or timer that has an event on it.

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## Module rinSystem.rinSockets

Offer functions for sockets that are compatible with the app framework

### Functions

<a href="#">addSocket (sock, callback)</a>	Add a socket to the socket list
<a href="#">socketCallback (sock)</a>	Run the callback function associated with a socket
<a href="#">removeSocket (sock)</a>	Remove a socket from the socket list

### Functions

#### [addSocket \(sock, callback\)](#)

Add a socket to the socket list

##### Parameters:

- *sock*: Socket to add to the list
- *callback*: Callback for the socket

#### [socketCallback \(sock\)](#)

Run the callback function associated with a socket

##### Parameters:

- *sock*: Socket whose callback function should be executed.

#### [removeSocket \(sock\)](#)

Remove a socket from the socket list

##### Parameters:

- *sock*: Socket to remove from the list

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## Module rinSystem.rinTimers

Offer functions for timers that are compatible with the app framework

### Functions

<a href="#">addTimer (time, delay, callback, ...)</a>	Add a timer to the timer list
<a href="#">removeTimer (key)</a>	Remove a timer from the timer list
<a href="#">getSoonest ()</a>	Get the time until the next timer expires
<a href="#">runKey (key)</a>	Attempt to run a timer designated by the key.

### Functions

#### [addTimer \(time, delay, callback, ...\)](#)

Add a timer to the timer list

##### Parameters:

- *time*: Time until the timer will go off (milliseconds)
- *delay*: Initial delay for timer
- *callback*: Function to run when timer is complete
- ....: Function variables

##### Returns:

Timer key

#### [removeTimer \(key\)](#)

Remove a timer from the timer list

##### Parameters:

- *key*: Key for a timer

##### Returns:

key if success, nil and error if otherwise

#### [getSoonest \(\)](#)

Get the time until the next timer expires

##### Returns:

Timer key

#### [runKey \(key\)](#)

Attempt to run a timer designated by the key.

##### Parameters:

- *key*: Timer key given by add timer

##### Returns:

true is timer callback ran, false if it did not

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